

Q81. The error between the mean of finite data set and mean of infinite data set is known as

- True error of the mean
- Standard error of the mean
- Finite error
- Infinite error

Ans. 2

Q82. In a measurement system,

A single measurement components may have both random errors and systematic errors
A measurement system consists of several components with each component having separate errors

- Both the statement (1) & (2) are true
- Neither statement (1) nor statement (2) is true

Ans. 3

Q83. If the degree of damping of an instrument should be adjusted to a value which is sufficient to enable the pointer to rise quickly to its deflected position without overshooting is called as

- Overdamped
- Dead beat
- Underdamped
- None of these

Ans. 2

Q84. Due to overdamping, the instrument will become

- Slow
- Lethargic
- Fast
- Both (1) and (2)

Ans. 4

Q85. While measuring resistance by the voltmeter – ammeter method, the maximum possible percentage error in the voltmeter and ammeter are $\pm 1.8\%$ and $\pm 1.2\%$ respectively. Then the maximum possible percentage error in the value of resistance will be

- $\pm 3\%$
- $\pm 4\%$
- $\pm 4.2\%$
- $\pm 4.8\%$

Ans. 1

Q86. If the resistance in a circuit is given by $80 \Omega \pm 0.2\%$ and the current flowing through it is $5A \pm 0.1\%$, then the uncertainty in the power will be

- $\pm 0.2 \%$
- $\pm 0.4 \%$
- $\pm 0.6 \%$
- $\pm 0.8 \%$

Ans. 2

Q87. When a 100 V moving iron voltmeter is of accuracy class 1 – 0 is used in a circuit, it reads 50 V. Then the maximum possible percentage error in the reading is

- 1 %
- 2 %
- 2.5 %
- 3 %

Ans. 2

Q88. In liquid crystal displays, the liquid crystal exhibits properties of

- Liquid
- Solids
- Gases
- Both (1) and (2)

Ans. 4

Q89. In light emitting diode, the available light emitting region is

- Less than 2.5 mm
- From 2.5 to 25 mm
- Greater than 25 mm
- Greater than 50 mm

Ans. 2

Q90. Resolver works on the principal of mutual inductance variation. It is mainly used for the measurement of

- Linear displacement
- Non – linear displacement
- Rotary motion
- All of these

Ans. 3